

① a. Note that, for  $K\alpha = \text{integer}$

$$\sum_{n=0}^{N-1} e^{2\pi i K\alpha n} = N, \text{ and for } K\alpha \neq \text{integer}$$

$$\left| \sum_{n=0}^{N-1} e^{2\pi i K\alpha n} \right| = \left| \frac{e^{2\pi i K N \alpha} - 1}{e^{2\pi i K \alpha} - 1} \right| \leq \frac{2}{|e^{2\pi i K \alpha} - 1|}$$

Therefore  $\lim_{N \rightarrow \infty} \frac{1}{N} \sum_{n=0}^{N-1} e^{2\pi i K\alpha n} = 0$  for  $K\alpha \neq \text{int}$ ,

$$\begin{aligned} \text{and } \langle A \rangle_{\text{time}} &= \lim_{N \rightarrow \infty} \frac{1}{N} \sum_n \sum_K \tilde{A}(k) \exp[2\pi i k(x_0 + n\alpha)] \\ &= \tilde{A}(k=0) + \sum_{K \neq 0} \tilde{A}(k) e^{2\pi i k x_0} \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{n=0}^{N-1} e^{2\pi i k n \alpha} \\ &= \tilde{A}(k=0) \end{aligned}$$

$$b. \langle A \rangle_{\text{space}} = \int_0^1 dx \sum_K \tilde{A}(k) e^{2\pi i k x} = \tilde{A}(k=0)$$

$$\textcircled{2} \quad \tilde{M}(y) = g(M(g^{-1}(y)))$$

$$\begin{aligned} \Rightarrow \tilde{M}'(y) &= \frac{d}{dy} \tilde{M}(y) = g'(M(g^{-1}(y))) M'(g^{-1}(y)) (g^{-1})'(y) \\ &\quad \text{(by chain rule)} \\ &= g'(M(x)) M'(x) [g'(x)]^{-1} \\ &\quad \text{(by inverse function theorem)} \end{aligned}$$

$$\text{Now } h = \int_0^1 dx \rho(x) \ln |M'(x)|$$

$$\text{and } \tilde{h} = \int_0^1 dy \tilde{\rho}(y) \ln |\tilde{M}'(y)|, \text{ but } dx \rho(x) = dy \tilde{\rho}(y)$$

$$\Rightarrow \tilde{h} = h + \int dx \rho(x) \ln \left| \frac{g'(M(x))}{g'(x)} \right|$$

But recall  $\rho(x)$  is invariant under the map  $M$ ,  
which means  $\int dx \rho(x) [f(M(x)) - f(x)] = 0$ ,  
(for any function  $f$ )

so in particular

$$\int dx \rho(x) [\ln |g'(M(x))| - \ln |g'(x)|] = 0$$

and therefore  $\tilde{h} = h$

$$(3) \quad \begin{pmatrix} x \\ y \end{pmatrix} \rightarrow T \begin{pmatrix} x \\ y \end{pmatrix} \pmod{5} \quad T = \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix}$$

- Orbit of length 1 (fixed point)

$$x + y = x \pmod{5} \Rightarrow y = \text{integer}$$

$$x + 2y = y \pmod{5} \Rightarrow x = -y \pmod{5} = \text{integer}$$

$$\text{Therefore } (x, y) = (0, 0) \pmod{5}$$

- Orbits of length 2 (fixed points of  $T^2$ )

$$T^2 = \begin{pmatrix} 2 & 3 \\ 3 & 5 \end{pmatrix} \Rightarrow \begin{aligned} 2x + 3y &= x \pmod{5} \\ 3x + 5y &= y \pmod{5} \end{aligned}$$

$$\Rightarrow x + 3y = u \quad 5y = 3u - u = \text{integer}$$

$$3x + 4y = m \quad 5x = 3m - 4u = \text{integer}$$

Aside from  $(x, y) = (0, 0)$ , the other solutions in  $\mathbb{Z} \times \mathbb{Z}$  are

$$\left(\frac{1}{5}, \frac{3}{5}\right) \quad (u=2, m=3)$$

$$\left(\frac{2}{5}, \frac{1}{5}\right) \quad (u=1, m=2)$$

$$\left(\frac{3}{5}, \frac{4}{5}\right) \quad (u=3, m=5)$$

$$\left(\frac{4}{5}, \frac{2}{5}\right) \quad (u=2, m=4)$$

orbits are:

$$\left(\frac{1}{5}, \frac{3}{5}\right) \rightarrow \left(\frac{4}{5}, \frac{2}{5}\right) \rightarrow \left(\frac{1}{5}, \frac{3}{5}\right)$$

$$\left(\frac{2}{5}, \frac{1}{5}\right) \rightarrow \left(\frac{3}{5}, \frac{4}{5}\right) \rightarrow \left(\frac{2}{5}, \frac{1}{5}\right)$$

- Orbits of length 3 (fixed points of  $T^3$ )

$$T^3 = \begin{pmatrix} 5 & 8 \\ 8 & 13 \end{pmatrix} \Rightarrow \begin{aligned} 5x + 8y &= x \pmod{5} \\ 8x + 13y &= y \pmod{5} \end{aligned}$$

$$\Rightarrow 4x + 8y = u \quad \Rightarrow 4y = 2u - u$$

$$8x + 12y = m \quad 4x = 2m - u$$

Therefore  $4x$  and  $4y$  must be integers - and any  $(x, y)$  where  $4x$  and  $4y$  are integers is a solution:

$$\begin{aligned} x &= 0, \frac{1}{4}, \frac{1}{2}, \frac{3}{4} \\ y &= 0, \frac{1}{4}, \frac{1}{2}, \frac{3}{4} \end{aligned} \Rightarrow \text{excluding } (x, y) = (0, 0), \text{ there are } 4^2 - 1 = 15 \text{ solutions, and therefore } 15/3 = 5 \text{ orbits of length 3.}$$

4a)  $M(x) = rx - rx^2$  If  $M(x) = x$ , then

$$0 = (r-1)x - rx^2 \Rightarrow \text{either } x=0 \text{ or } x = \frac{r-1}{r}$$

Therefore, for  $x \in I = [0, 1]$ , fixed points are

$$x_0 = 0 \text{ for all } r$$

$$x_0 = \frac{r-1}{r} \text{ for } r \geq 1$$

Stability: At  $x_0 = 0$ ,  $M'(x_0) = r$

$$x_0 = \frac{r-1}{r}, M'(x_0) = r - 2rx_0 = 2 - r$$

Therefore,

Fixed point at  $x_0 = 0$  is  $\begin{cases} \text{stable } r < 1 \\ \text{unstable } r > 1 \end{cases}$

Fixed point at  $x_0 = \frac{r-1}{r}$  is  $\begin{cases} \text{stable } 1 < r < 3 \\ \text{unstable } r > 3 \end{cases}$

$$b) M^2(x) = M(M(x)) = r[r x(1-x)][1 - r x(1-x)]$$

$$= -rx^2(rx^3 - 2rx^2 + (r+1)x - 1)$$

Fixed point of  $M^2(x)$ :  $M^2(x) = x \Rightarrow$  either  $x=0$

$$\text{or } rx^3 - 2rx^2 + (r+1)x - 1 + \frac{1}{r^2} = 0$$

One solution is  $x_0 = \frac{r-1}{r}$ , as in (a) above

the other 2, for 3.3 are  $x_1 = .4794$

$$x_2 = .8236$$

(found with Mathematica, or you could divide out  $x - \frac{r-1}{r}$  to obtain a quadratic equation)

Stability coefficient is

$$M'(x_1) M'(x_2) = r^2 (1 - 2x_1)(1 - 2x_2) = \dots = -.2900$$